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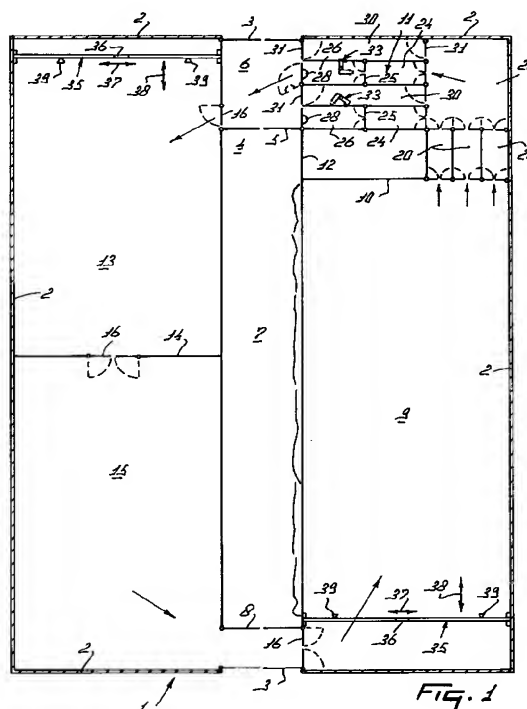
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**NL-3155 ZG Maasland (NL)**(54) **A construction for automatically milking animals, such as cows.**

(57) The invention relates to a construction for automatically milking animals, such as cows, comprising a milking parlour (26) and a milking robot (33). The milking parlour (26) is accommodated in an enclosed area (1) which comprises several sub-areas (9,11,13,15), in which groups of animals can be accommodated and wherein the animals are to move to the milking robot (33) from a given sub-area (9,11,13,15). Thus, the groups of animals can be milked immediately one after the other.

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The invention relates to a construction for automatically milking animals, such as cows, comprising a milking parlour and a milking robot. With such construction, it sometimes may be difficult to ensure that all animals will be milked by the milking robot in time.

The invention has for its object to provide a construction in which the above disadvantage will at least be obviated as much as possible.

According to the invention the construction is therefore characterized in that the milking parlour is accommodated in an enclosed area, which area comprises several sub-areas, in which groups of animals can be accommodated and wherein the animals are to move to the milking robot from a given sub-area. This system provides the advantage that a group of animals can be milked automatically, while another group of animals, after having been milked, can rest for a while before being milked again. It is of further advantage if the milking system will comprise two or more milking robots and/or if the cows are being milked by the robot without the supervision of a person.

In accordance with a further feature of the invention, at least two milking robots are present in the milking parlour, one of which milking robots may automatically be switched into operation when the other milking robot is no capable of handling the desired number of animals in the desired time.

In accordance with a further feature of the invention, the construction includes at least one expelling implement for moving the animals in the construction, which expelling implement can produce one or more acoustic signals and one or more electroshocks. Using the expelling implement, it is possible to drive a group of animals in its totality from one sub-area to another sub-area. In order to check whether a group of animals has left a given sub-area, the construction includes, in accordance with a further feature of the invention, a plurality of sensors, by means of which the presence and/or the absence of the animals in an area can be established.

In accordance with a still further feature of the invention, the area is divided into sub-areas in such a manner that groups of animals can be milked immediately one after the other in the milking parlour. For that purpose, the area comprises  $N+1$  sub-areas for  $N$  groups of animals. During milking of one group of animals, the sub-area in which the group of animals to be milked is located, communicates via the milking parlour in one direction with another sub-area. The group of animals to be milked can therefore only reach the other sub-area via the milking parlour. After the last animal of a group of animals has arrived in the other sub-area via the milking parlour, the sub-area is filled again with a new group of animals and the group of milked

animals is simultaneously moved to an other sub-area. By circulating the groups of animals through the several sub-areas, it is thus possible for groups of animals to be automatically milked e.g. three times in every 24 hours' period. The construction as per the invention may comprise a building, a fenced yard, a cow shed and/or other places for dairy animals.

For a better understanding of the invention and to show how the same may be carried into effect, reference will now be made, by way of example, to the accompanying drawings, in which:

Figure 1 is a plan view of the construction for automatically milking animals;

Figure 2 is a side view of a holder enclosing milking tubes and lines;

Figure 3 is a plan view of the holder, in which the milk tubes and pulsation lines have been provided;

Figure 4 is a cross-sectional view of the holder taken on the line IV-IV in Figure 3;

Figure 5 is a front view of the holder taken on the line V-V in Figure 2.

The plan view shown in Figure 1 shows a stable or dwelling place 1 for milch animals, which is entirely or partly enclosed by a number of walls 2. In this embodiment, the walls 2 are provided on both sides of the stable 1 with a set of doors 3, through which the animals can be brought inside or outside. In this case the stable is a closed loose house, wherein the animals are staying in the house. The invention, however, also relates to an open loose house, in which, for example, one of the walls 2 is entirely or partly omitted, so that the animals can freely go inside or outside via a passage located next to the stable. In the embodiment shown, there is located in the centre of the smallest dimension of the stable 1 a feeding passage 4 which extends through a portion of the stable 1 and is separated from the area located on either side thereof by a wall having vertical rods or similar barriers, through which the animals can pass their heads so as to obtain fodder from the feeding passage 4. The feeding passage 4 is divided into two sections by swing doors 5, a first section 6 being bounded by the doors 3 in the wall 2 and the swing doors 5, while the second section 7 is bounded by the swing doors 5 and a set of further doors 8 at the end of the feeding passage 4. Taken in the longitudinal direction, the first section 6 is, as regards its dimensions, significantly smaller than the second section 7; the length of the first section 6 amounts to approximately 1/6 of the length of the second section 7.

On either side of the feeding passage 4, the stable 1 has a number of sub-areas in which the animals can be housed. The first sub-area 9 is bounded by two walls 2, the wall with vertical rods

or similar barriers and a first partition 10. The length of the area 9 between the first partition and the wall 2 amounts to approximately 4/5 of the length of the longest side of the stable 1. The third area 11 of the stable 1 is bounded by walls 2, a first partition 10 and a second partition 12. The length between the first partition 10 and the wall 2 of the third area 11 amounts to approximately 1/5 of the length of the longest side of the stable 1. The third area 11 borders by means of the second partition 12 on the first area 6.

At the other side of the feeding passage 4, the stable 1 has a third sub-area 13 which is bounded by two walls 2, the wall with vertical rods or similar barriers and a second partition 14. The second partition 14 forms a division between the third sub-area 13 and a second sub-area 15. The second sub-area 15 is bounded, as is also the third sub-area 13, by walls 2, the wall with vertical rods or similar barriers and the second partition 14. The length of the third sub-area 13 and the second sub-area 15 amounts to approximately half the length of the longest side of the stable 1.

The partitions between the sub-areas are further provided with first doors 16, through which the animals have access from one sub-area to an other sub-area. In addition, three sanitation areas 20, each having room for one animal, are arranged in the third area 11. In the sanitation areas 20, the animals can be cleaned and/or disinfected by a (non-shown) cleaning/disinfecting implement. After the animals have been treated in the sanitation areas 20, the animals can move to an intermediate area 22 positioned in the second sub-area 11. From the intermediate area 22 the animal can move to two adjacently positioned waiting boxes 24. The waiting boxes 24 have a second door 25, which allows the animals to enter milking boxes 26 positioned in the extension of the waiting boxes 24. The milking boxes 26 are provided with a feeding trough 28. By means of a (non-shown) fodder dosing system, concentrated feeding material can be provided to the animals in the feeding trough 28. In addition to each of the waiting boxes 24 and the milking boxes 26 there is a passageway 30 having third doors 31. Located in the passageway 30, near each of the milking boxes 26, there is a milking robot 33, by means of which an animal standing in the milking box 26 can be milked automatically. In operation, the milking operation is normally performed with one milking robot, and the second milking robot is not used until the first milking robot cannot duly milk the number of animals.

Both on the left-hand side and on the right-hand side of the feeding passage 4, an expelling implement 35 extends through the overall width of the stable 1, bounded by the wall 2 and the wall having vertical rods or similar barriers. The expel-

ling implement 35 preferably includes a telescoping arm 36 which extends in the lateral direction over the sub-areas 9, 13, 15 and is suspended from a travelling trolley construction in the stable 1. The arm 36 is movable in the direction indicated by arrows 1. The arm 36 is equipped with at least one descending wire to which current can be applied (electric fence voltage). The arm 36 can be moved in the direction indicated by arrows 38 in the longitudinal direction of the stable 1 along a (non-shown) rail, as is customary for a travelling trolley. In addition to the descending wire, the arm 36 is provided with means 39 which supply light signals and/or acoustic signals and can co-operate with the descending wire. When the animals are to be driven, for example, because the animals are to be moved from one sub-area to another, an acoustic and/or light signals is supplied by the light and/or acoustic means 39, which is an indication to the animals that they are to leave the relevant sub-area. If necessary, the expelling implement 35 is moved forwards in the longitudinal direction of the stable 1, the animals still present in the relevant sub-area being induced by the wire, which is suspended from the arm 36 and on which there is an electric charge, to move to the other sub-area.

The construction for automatically milking animals operates as follows:

As has already been stated hereinbefore, the stable 1 comprises in this embodiment three sub-areas. A hundred cows are, for example, accommodated in the sub-areas, the animals being subdivided into two groups of fifty animals, each group being housed in separate sub-areas, so that the animals of this group can successively be milked in defined time intervals. The length of the time intervals is determined by the number of milking runs per 24 hours' period. Starting from the assumption that there are, for example, three milking runs per 24 hours' period, this consequently means that the length of the time intervals corresponds to eight hours, in other words: after eight hours a group of previously milked animals is milked again. This means that in each 24 hours' period each group of fifty animals all pass three times through all the three sub-areas 9, 13, 15.

As a starting point, let it be assumed that the first group of fifty animals is in the second sub-area 15 and the second group of fifty animals is accommodated in the first sub-area 9. The animals of the second group can move at random from the first sub-area 9 to the sanitation areas 20, in which the udder and/or the teats of in this case always a maximum of three animals can be cleaned. After the udder and/or the teats of an animal have been cleaned, the animal leaves the sanitation area 20 and arrives in the intermediate area 22, so that a number of animals can be present in the intermedi-

ate area 22. From the intermediate area 22 always one animal can enter the waiting box 24 when this box is free or becomes free. From the waiting box 24 the animal can thereafter walk to the milking box 26 when it is released by the second door 25. In the milking box 26, the animal is identified by a (non-shown) animal identification system. On the basis of the animal identification data, a quantity of concentrated fodder matched to the relevant animal is deposited in the feeding trough 28 by a fodder dosing system. In addition, the milking robot 33 is energized by a (non-shown) computer, whereafter the animal is milked automatically.

If at a given instant it should appear that too many animals arrive in the intermediate area 22, then the other milking robot 33 can temporarily be switched-on with the object of reducing in that manner the waiting time of the animals in the intermediate area 22.

After the computer has determined that the animal has been milked, the animal leaves the milking box 26 and passes via the first area 6 into the third sub-area 13. In the third sub-area 13, the animal can optionally take some rest in (non-shown) rest boxes. Each of the fifty animals present in the first sub-area 9 can in this manner go voluntarily and in any random sequence to the third sub-area 13, so that after four hours all the fifty animals of the second group may have moved via the milking robot 33 to the third sub-area 13. It might, however, also occur that one or more animals, for whatever reason, remain behind in the first sub-area 9. This is, however, undesirable, since the remaining animals then would mix with the other, first group of animals which, after the above-mentioned four hours have elapsed, arrive in the first sub-area 9. To prevent intermingling of groups of animals, it is therefore checked, after the four hours have elapsed, with the aid of a plurality of (non-shown) sensors whether animals of the second group are still present in the first sub-area 9. The sensors may be infrared sensors, using which it can be determined on the basis of the animals' body heat whether animals are still present in the relevant sub-area. Should the situation now be such that animals have still stayed behind in the first sub-area 9, then by giving light signals and/or acoustic signals in the relevant area the animals are thereafter induced to leave the first sub-area 9. If after due time it appears that the animals do not react to these signals, then the expelling implement 35 can be advanced step-by-step in the longitudinal direction of the first sub-area towards the sanitation areas 20. The animals still present in the first sub-area 9 are then incited by the live wires suspended from the arm 36 to go to the sanitation areas 20. When all the fifty animals of the second group have left the first sub-

area 9, the way is cleared by opening the door 16 between the second sub-area 15 and the first sub-area 9, whereafter the first group of fifty animals can move to the first sub-area 9. The animals of the first group will then usually go voluntarily to the first sub-area 9, because they instinctively sense that they can go from the first sub-area 9 to the milking box 26, where they are milked and supplied with concentrated fodder. A different possibility to lure the animals to the first sub-area 9, is to deposit green forage in the feeding passage 4 near the walls with vertical rods. After some time it is also here checked by means of sensors whether all the animals of the second group have gone to the first sub-area 9; if there are stragglers then they are forced, in the manner already described in the foregoing, using the expelling implement 35 to leave the sub-area. When the second sub-area 15 is empty, the door 16 between the second sub-area 15 and the first sub-area 9 is closed. Simultaneously the door 16 between the third sub-area 13 and the second sub-area 15 is opened and the second group of animals, which at that moment is present in the third sub-area 13, are notified by means of light signals and/or acoustic signals to move to the second sub-area 15. Straggling animals can also here, after some time, be actively forced by means of the expelling implement 35 to move to the second sub-area 15. The second group of fifty animals is given a four hours' rest in the second sub-area 15, whilst the first group of animals in the first sub-area 9 is given four hours' time to move via the milking box 26 to the third sub-area 13 which is empty at that moment.

After four hours it is assumed that the first group of animals has been milked and it is consequently assumed that the entire group has moved to the third sub-area 13, whereafter the second group of animals can again enter the first sub-area 9. Thereafter the rotation of the two groups of animals through the three sub-areas can start again. Thus, the two groups of animals can be milked immediately one after the other in the milk box(es) 26.

It will be obvious that the invention is not limited to the embodiment described in the foregoing, in which the stable 3 comprises three sub-areas for two groups of animals, but that the stable 1 may alternatively comprise  $N + 1$  sub-areas for  $N$  groups of animals.

Figures 2 to 5 show a detail of the milking robot 33 arranged in the stable 1. Figure 2 is a cross-sectional view of one end of the robot arm 40. The robot arm 40 comprises a box-like holder 41 containing milk tubes 42 and pulsation tubes 43. Arranged near the end of the holder 41 is a laser device 44, with the aid of which the position of the teats of an animal can be determined. Moreover,

four teat cups 45 are provided near the end of the holder 41. Each of the teat cups 45 bears by means of its bottom end on a supporting element 46, which has a conical seat. The bottom side of the teat cups 45 is of such a design that it fits in the conical seat. Each supporting element 46 is mounted capably of pivoting about a shaft 47, which shaft 47 is inserted through a bore near the bottom side of each supporting element 46. The shaft 47 is connected by means of three lugs 57 to the bottom side of the holder 41. Positioned between each of the supporting elements 46 and the holder 41 is a spring 48, by means of which the supporting element 46, which has a stop plane 49, is pulled up against the bottom side of the holder 41. Arranged at the bottom side of the teat cups 45 is a pulling member 50, constituted by cables or cords, produced of a suitable flexible material. The pulling member 50 is passed through a hole drilled in the supporting element 46, as well as through a hole drilled in the holder 41. The pulling member 50 extends to as far as the end of a piston rod 51 of a cylinder 52, where it is attached to a cap 55. Figure 4 shows that four cylinders 52 have been disposed in a side-by-side relationship on the bottom of the holder 41. Through the overall width of the holder 41 a metal plate 53 extends above the cylinders 52. Four guide strips 54 are disposed in the longitudinal direction of the metal plate 53. The guide strips 54 constitute a longitudinal guideway for the round caps 55, which are provided at the end of the piston rod 51. The caps 55 have a notch, in which the guide strips 54 fit. By energizing the cylinders 52 the caps 55 are moved along the guide strips 55 and the teat cups 45 are pulled into the conical seats of the supporting elements 46 by means of the flexible pulling members 50.

In the length-wise direction of the holder 41, three partitions 56 are arranged with equal inter-spaces between the plate 53 and the upper side of the holder 41. The partitions 56 are positioned approximately in the midway point of the holder 41 and have a length which amounts to approximately 1/3 of the overall length of the holder 41. Consequently, the three partitions 56 partly divide the space above the plate 53 into four separate spaces. In each of these four spaces a milk tube 42 and a pulsation tube 43 of a teat cup 45 are situated. The pulsation tube 43 and the milk tube 42 are positioned in the holder 41 in such a manner that they form a loop. The milk tubes 42 and the pulsation tube 43 extend from the teat cups 45 in the horizontal direction to approximately near the other end of the holder 41. The milk tubes 42 and the pulsation tubes 43 are supported near the plate 53 by three longitudinal guideways 58 which are provided remote from each other in the holder 41. The longitudinal guideways 58 include shafts 59

arranged between the two lateral walls of the holder 41. Four tubes 60, which are each independently rotatable about the shaft 59, are inserted over each shaft 59. A milk tube 42 and a pulsation tube 43 bear on each tube 59.

In the holder 41, near that end that is remote from the teat cups 45, the milk tubes 42 and the pulsation tubes 43 are bent to the upper side of the holder 41 in such a way as to form half a circle. Near the upper side of the holder 41, the tubes 42 and 43 extend thereafter in parallel to the upper side of the holder 41 towards the laser device 44, to as far as U-shaped auxiliary members 61. The U-shaped auxiliary members 61 are applied against the interior wall of the holder 41. Using the U-shaped auxiliary members 61, the milk tubes 42 and the pulsation tubes 43, respectively, are led back through an angle of 180° towards the rear side of the holder 41 where the tubes are folded through 90° towards a carrier 62.

A box girder 63 is disposed against the side of the holder 41, in the vertical direction. At the upper and bottom sides, the box girder 63 is covered by metal plates 64. At the upper and bottom sides, the box girder 63 is clamped between a carrier 62 designed as a fork. The carrier 62 comprises a box girder 65, the end of which is provided with a U-shaped plate 66. The bottom and upper sides of the box girder 63 are clamped by the U-shaped plate 66. At both the upper and the bottom side of the U-shaped plate 66, holes 67 are drilled, through which bolts 68 are inserted. The bolts 68 are relatively short and are provided with thread near the bottom end only. The bolts 67 are screwed in the bottom and upper side, respectively, of the box girder 63, thus forming a pivot shaft, about which the holder 41 can pivot relative to the carrier 62. The upper sides of the box girder 63 and the end of the carrier 62 are provided with apertures 69. The milk tubes 42, the pulsation tubes 43 and an electric wire 70 are passed through the apertures 69. Near the end of the box girder 63, a plurality of supporting elements 71 are positioned, which support the milking tubes 42, the pulsation tubes 43 and the electric wire 70.

An angular strip 72 is provided in the corner between the box girder 63 and the holder 41. The end of a piston rod 73 of a cylinder 74 is secured to the angular strip 72.

The cylinder 74 is arranged parallel to the carrier 62 and is accommodated in a housing 75. By means of the cylinder 75, the holder 41 can be pivoted with respect to the carrier 62 about the vertical pivot shaft formed by the bolts 68.

A nose-shaped cast iron member 76 is disposed near the end of the holder 41. The nose-shaped cast iron member 76 comprises a rectangular housing which at one end is provided with

lugs 77. The housing is screwed to the interior walls of the holder 41 by means of the lugs 77. The height of the nose-shaped cast iron member 76 amounts to approximately half the height of the holder 41. The nose-shaped housing 76 extends from the leading side of the holder 41 to above the supporting elements 46. The laser device 44 is located near the leading side of the holder 41. The laser device 44 is partly disposed in the housing of the nose-shaped cast iron member 76. The upper portion of the laser device 44 extends to beyond the housing of the nose-shaped cast iron member 76 and to just above the holder 41. The two upper halves of the side edges of the nose-shaped cast iron member 76 are provided with bevelled, upwardly extending triangular ribs 78. The triangular ribs 78 extend from the upper edge of the nose-shaped cast iron member 76 to the exterior, so that the largest width is obtained near the midway point of the side wall of the nose-shaped cast iron member 76. Between the lower side of ribs 78 and the upper side of the outermost supporting elements 46 there is a space, in which the milk tubes 42 and the pulsation tubes 43 of the outermost teat cups 45 are positioned. The outermost milk tubes 42 and the outermost pulsation tubes 43 are shielded, seen from above, by the ribs 78, so that, when a cow kicks, for example, with its leg from above against the leading side of the holder 41, the tubes are shielded by the ribs 78. The milk tubes 42 and the pulsation tubes 43 of the two central teat cups 45 extend through the housing of the nose-shaped cast iron member 76 and are consequently protected by the housing itself from, for example, kicking by an animal (Figure 3, 5).

The leading side of the nose-shaped cast iron member 76 is, in a plan view, in the shape of a trapezium (Figure 3). The oblique sides of the nose-shaped cast iron member 76 are provided with curved planes of contact 79, against which the teat cups 45 bear. In the curved planes of contact 79 magnets 80 are provided, with the aid of which the teat cups can be moved upwardly and/or downwardly relative to the curved plane of contact 79.

The construction for automatically milking animals operates as follows:

After a cow has entered the milking box 26, the robot arm 40 is swiveled to under the animal. The position of the cow's teats is determined by means of the laser device 44. By energizing the cylinder 74, the holder 41 is pivoted about the bolts 68 until the teat cups are positioned under the cow's teats. Thereafter, the pressure is removed from one of the cylinders 52, as a result of which the pulling member 50 is not tightened any more and consequently the associated teat cup 45 is not pulled into the conical seat of the supporting element 46. Simultaneously, the magnet 80 of the relevant teat

cup 45 is energized and the teat cup 45 is moved upwardly along the plane of contact 79 to as far as a teat. The relevant teat cup 45 is at that moment evacuated, so that the teat cup 45 is firmly attached to the teat. After the first teat cup 45 has been connected, the other teat cups 45 follow. Usually, the two centremost teat cups 45 are connected first and thereafter the two outermost teat cups 45. In Figure 3, interrupted lines illustrate the possible configuration of the teat cups 45 after they have been connected to the teats of an animal. During connection of the teat cups 45, the holder 41 moves relative to the connected teat cup(s) 45, and consequently a portion of the milk tube 42 and the pulsation tube 43 will move relatively with respect to the holder 41. In the present invention, this can be effected in a particularly advantageous manner, as the milk tube 42 together with the pulsation tube 43 have been disposed slidably in the holder 41. During the motion of the holder 41, the milk tubes 42 and the pulsation tubes 43, of the teat cups 45 connected to the teats of an animal, are wound into or out of the holder 41 along the guideways 58. The loops in the milk tubes 42 and the pulsation tubes 43 render it possible for the tubes to slide in the longitudinal direction of the holder 41 and at the same time provide that the tubes can be relatively long and can still be accommodated in the holder 41 in a compact manner.

Uncoupling the teat cups 45 is effected by removing the vacuum in the teat cups 45 and the simultaneously energization of the cylinders 52, in response to which the piston rods 51 are moved, so that the teat cups 45 are pulled into the conical seats of the supporting elements 46 by pulling members 50.

## Claims

1. A construction for automatically milking animals, such as cows, comprising a milking parlour and a milking robot, characterized in that the milking parlour is accommodated in an enclosed area, which area comprises several sub-areas, in which groups of animals can be accommodated and wherein the animals are to move to the milking robot from a given sub-area.
2. A construction as claimed in claim 1, characterized in that in the milking parlour there are at least two milking robots, one of the milking robots being automatically switchable into operation when the other milking robot is not capable of handling the desired number of animals in the desired time.

3. A construction for automatically milking animals, such as cows, comprising a milking parlour and a milking robot, characterized in that in the milking parlour there are at least two milking robots, one of the milking robots being automatically switchable into operation when the other milking robot is not capable of handling the desired number of animals in the desired time. 5
4. A construction as claimed in any one of the preceding claims, characterized in that the construction includes a cleaning area, in which the udder and/or the teats of an animal can be cleaned, this cleaning area being remote from the milking area. 10 15
5. A construction for automatically milking animals, such as cows, comprising a milking parlour and a milking robot, characterized in that the construction includes a cleaning area, in which the udder and/or the teats of an animal can be cleaned, this cleaning area being remote from the milking area. 20 25
6. A construction as claimed in any one of the preceding claims, characterized in that the construction includes a plurality of sensors, by means of which the presence and/or the absence of the animals in an area can be determined. 30
7. A construction for automatically milking animals, such as cows, comprising a milking parlour and a milking robot, characterized in that the construction includes a plurality of sensors, by means of which the presence and/or the absence of the animals in an area can be determined. 35 40
8. A construction as claimed in any one of the preceding claims, characterized in that the construction includes at least one expelling implement for driving one or more of the animals from one area to another area. 45
9. A construction for automatically milking animals, such as cows, comprising a milking parlour and a milking robot, characterized in that the construction includes at least one expelling implement for driving one or more of the animals from one area to another area. 50
10. A construction as claimed in any one of the preceding claims, characterized in that the expelling implement can produce one or more acoustic signals and/or light signals and one or more electroshocks. 55
11. A construction as claimed in any one of the preceding claims, characterized in that the area is divided into sub-areas in such a manner that the animals can be milked immediately one after the other in the milking parlour.
12. A construction for automatically milking animals, such as cows, comprising a milking parlour and a milking robot, characterized in that the milking parlour is accommodated in an area, which area comprises several sub-areas, in which groups of animals can be moved such and in which the area is arranged in such a way that the animals can be milked immediately one after the other in the milking parlour.
13. A construction as claimed in any one of the preceding claims, characterized in that the building includes a loose housing.
14. A construction as claimed in any one of the preceding claims, characterized in that the cows are milked automatically three times in every 24 hours' period.
15. A construction as claimed in any one of the preceding claims, characterized in that the area comprises N+1 sub-areas for N groups of animals.
16. A construction as claimed in claim 15, characterized in that the area can hold two groups of fifty animals.
17. A construction as claimed in any one of the preceding claims, characterized in that means are present, by means of which it can be determined automatically whether a further milking robot will be automatically be switched on when a group of animals cannot be milked in time.
18. A construction as claimed in any one of the preceding claims, characterized in that the area comprises three boxes, each having a cleaning implement for cleaning the teats and/or the udder of the animal.
19. A construction as claimed in any one of the preceding claims, characterized in that the construction includes a waiting box, for an animal before the animal will enter the milking box.
20. A construction as claimed in any one of the preceding claims, characterized in that the

area includes means for moving groups of animals with a fixed time interval from one sub-area to another.

21. A construction as claimed in claim 20, characterized in that the time interval, between which a group of animals is brought from a first to another sub-area, amounts to four hours. 5
22. A construction as claimed in any one of the preceding claims, characterized in that access to the milking parlour is at random for the animals of a group of animals. 10
23. A construction as claimed in any one of the preceding claims, characterized in that an animal identification system is present, with the aid of which it can be determined how much feed will be supplied to each animal. 15
24. A construction as claimed in any one of the preceding claims, characterized in that the area includes an expelling installation for driving one or a plurality of animals from a sub-area, the expelling installation comprising a sensor, by means of which it can be determined whether one or more animals is/are still present in a given sub-area. 20
25. A construction as claimed in claim 24, characterized in that the sensor is an infrared sensor. 25
26. A construction as claimed in claim 24 or 25, characterized in that the expelling installation comprises an overhead trolley, on which sensors have been arranged. 30
27. A construction as claimed in any one of claims 24 to 26, characterized in that the expelling implement has one or more wires, by means of which electric shocks can be produced when an animal comes into contact with the wire. 35
28. A construction as claimed in any one of claims 24 to 27, characterized in that the expelling implement includes means, with which acoustic signals can be supplied before the animal receives a shock via the wire. 40
29. A construction as claimed in any one of claims 24 to 28, characterized in that a light source is located near the wire, which lights up as soon as a wire approaches an animal. 45
30. A construction as claimed in any one of the preceding claims, characterized in that a milking robot is positioned in the area, in the manner described and illustrated in the drawings. 50
31. A construction as claimed in one or more of the preceding claims and/or described in the accompanying description and shown in the accompanying drawings. 55
32. A method of automatically milking animals, such as cows, in which the animals are subdivided into N groups, which are each accommodated in a separate area with the purpose of milking these groups one after the other in time intervals, whilst the length of the time intervals is determined by the number of milking runs per 24 hours' period and each group of animals N + 1 passes through sub-areas in a period of time corresponding to 24/K hours, wherein K represents the number of milking runs for each 24 hours' period.
33. A method as claimed in claim 32, characterized in that, before the animals are milked, the udder and/or the teats of the animals are cleaned.
34. A method as claimed in claim 32 or 33, characterized in that, during automatically milking of the animals, the animals are fed.
35. A method as claimed in any one of the preceding claims, characterized in that the groups of animals are driven from one sub-area to another sub-area in defined time intervals.
36. A construction for applying the method as claimed in claims 32 to 35, characterized in that the construction is of a design as claimed in any one of claims 1 to 31.



